**Z transform**

1. H(z)=
2. Generate transfer function.
3. Find the frequency response of system.
4. Find step response of system.
5. Check stability of system use two different Methods.
6. Find impulse response use two different Methods.

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A causal LTI system is described by the following difference equation:

y(n) = 0.81y(n − 2) + x(n) − x(n − 2)

1. Determine the system function H(z).
2. the unit impulse response h(n) .
3. the unit step response s(n).
4. Plot zeros and poles of this system.
5. the frequency response function H(ejw), and plot its magnitude and phase response.